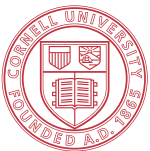




ECE 6775  
High-Level Digital Design Automation  
Fall 2023

**More CFG  
Static Single Assignment**



Cornell University



# Announcements

- ▶ Lab 2 is released

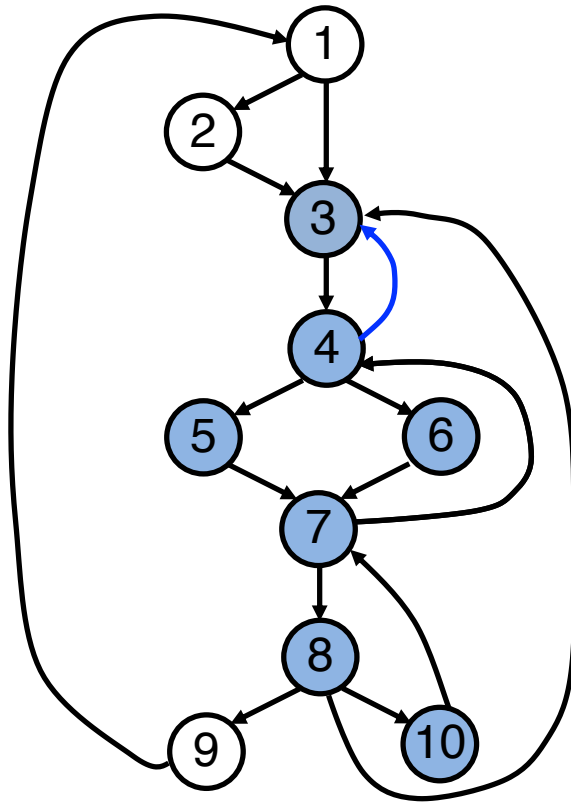
# Agenda

- ▶ More control flow analysis
  - Dominator tree
  - Dominance frontier
- ▶ Dataflow analysis – static single assignment (SSA)
  - SSA definition
  - PHI node ( $\Phi$ -node) placement
  - Code optimizations with SSA
- ▶ A brief overview of LLVM

# Review: Dominance Relation

- ▶ **Definition:** Let  $G = (V, E, s)$  denote a CFG, where
  - $V$  : set of nodes
  - $E$  : set of edges
  - $s$  : entry node andlet  $p \in V, q \in V$ 
  - $p$  **dominates**  $q$ , written  $p \leq q$ 
    - also written  $p \in \text{DOM}(q)$
  - $p$  **properly (strictly) dominates**  $q$ , written  $p < q$  if  $p \leq q$  and  $p \neq q$
  - $p$  **immediately (or directly) dominates**  $q$ , written  $p <_d q$  if  $p < q$  and there is no  $t \in V$  such that  $p < t < q$ 
    - also written  $p = \text{IDOM}(q)$

# Review: Finding Loops



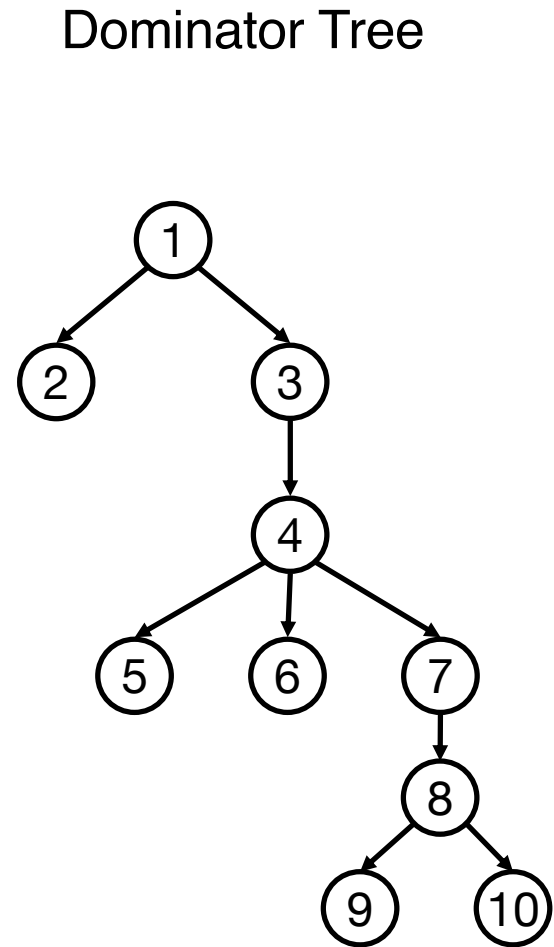
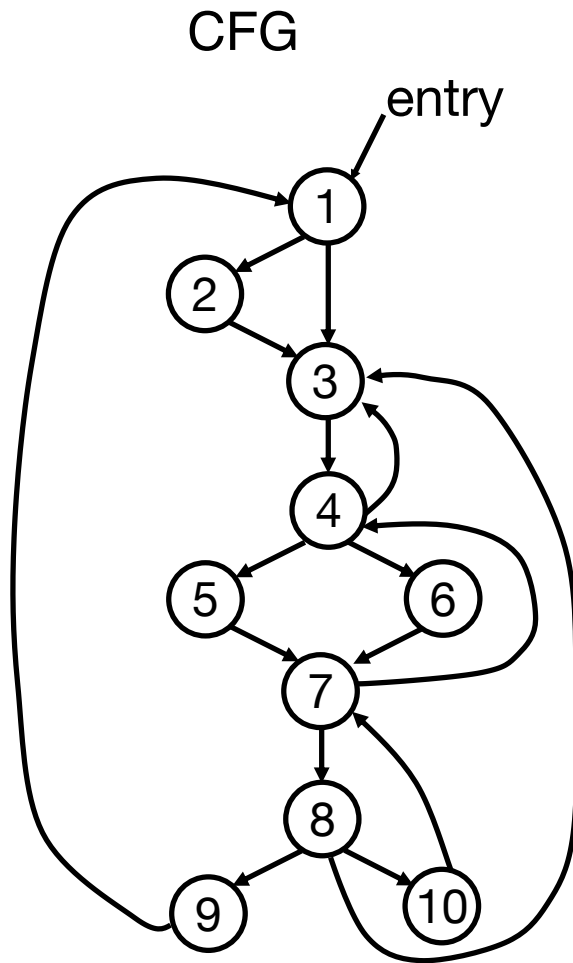
Find all back edges in this graph and the natural loop associated with each back edge

- (9,1) Entire graph
- (10,7) {7,8,10}
- (7,4) {4,5,6,7,8,10}
- (3,4) {3,4,5,6,7,8,10}

# Dominator Tree

- ▶ A node (basic block)  $N$  in CFG may have multiple dominators, but **only one of them will be closest to  $N$**  and be dominated by all other dominators of  $N$
- ▶ A dominator tree is a useful way to represent the dominance relation
  - The entry node  $s$  is the root
  - **Each node in the dominator tree is the immediate dominator of its children**
    - Each node  $d$  dominates only its descendants in the tree

# Example: Dominator Tree

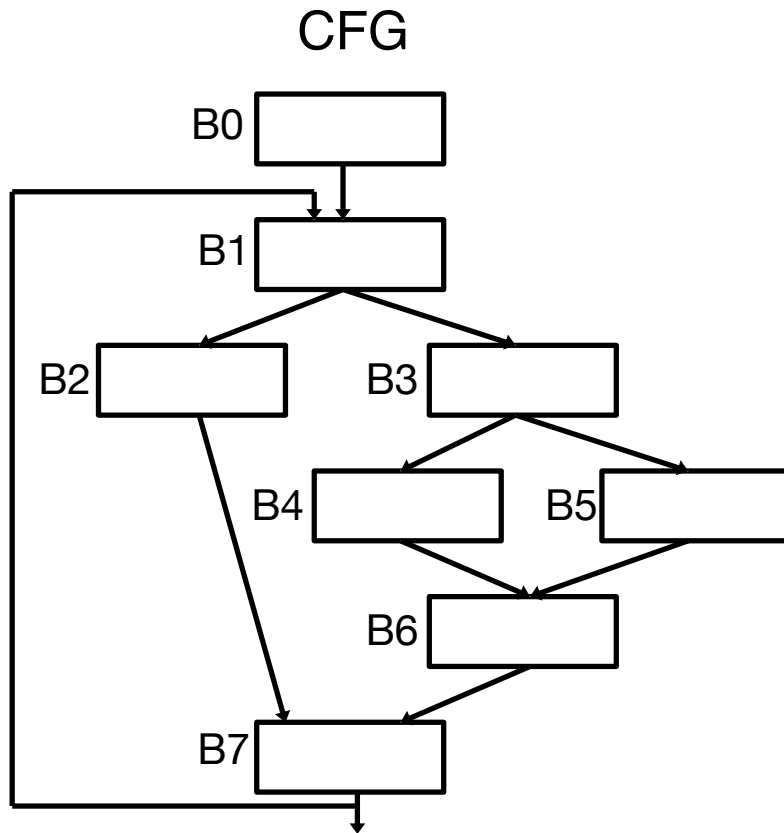


# Dominance Frontier

- ▶ A basic block  $q$  is in the **dominance frontier set (DF)** of basic block  $p$  if and only if
  - (1)  $p$  *does NOT strictly dominate*  $q$
  - (2)  $p$  *dominates some predecessor(s)* of  $q$If above two conditions hold,  $q \in \text{DF}(p)$
- ▶ Intuitively, for an  $q \in \text{DF}(p)$ ,  $q$  is almost strictly dominated by  $p$
- ▶ Useful for efficiently computing the SSA form



# Example: Dominance Frontiers



Dominance frontiers (DF)

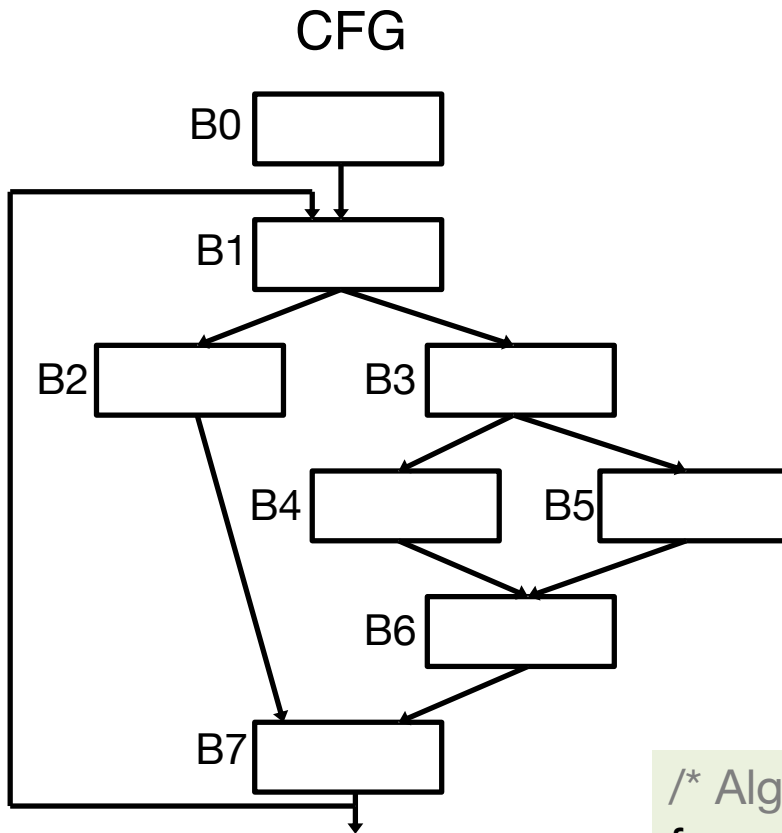
p	DF(p)
0	-
1	?
2	7
3	7
4	6
5	6
6	7
7	?

q is in the dominance frontier set (DF) of p iff

- (1) p does NOT strictly dominate q
- (2) p dominates some predecessor(s) of q

If above two conditions hold,  $q \in DF(p)$

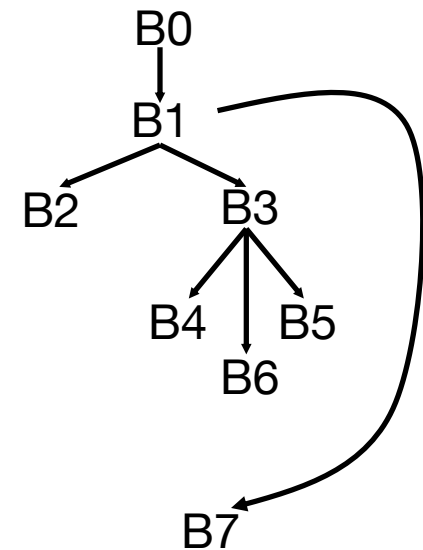
# Dominance Frontiers and Dominator Tree



Dominance frontiers (DF)

p	DF(p)
0	-
1	1
2	7
3	7
4	6
5	6
6	7
7	1

Dominator tree



<sup>1</sup>convergence point is a node in CFG with multiple predecessors

```

/* Algorithm to construct the DF sets */
foreach convergence point1 Q in CFG
  foreach predecessor X of Q in CFG
    Run up to Y=IDOM(Q) in the dominator tree,
    adding Q to DF(P) for each P between [X, Y)
  
```

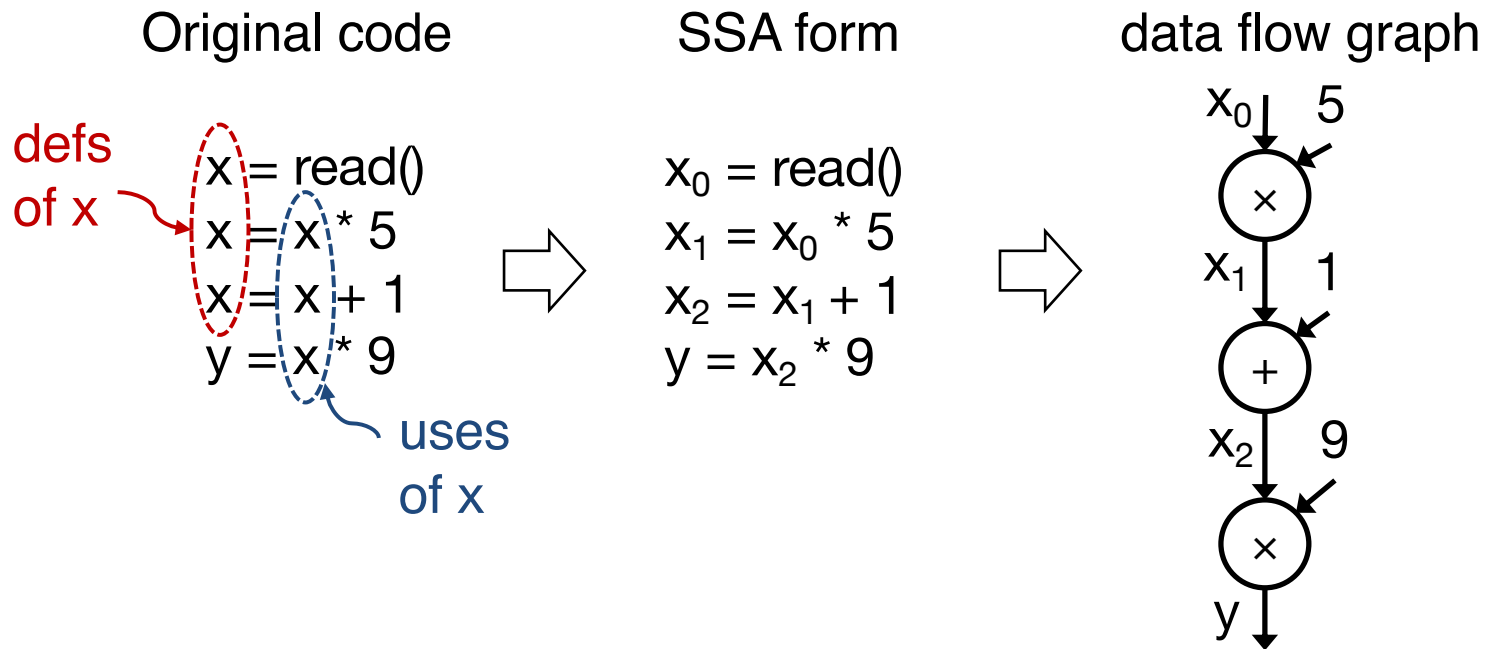
Only convergence points are added to the DF sets!

# Static Single Assignment

- ▶ Static single assignment (**SSA**) form is a restricted IR where
  - Each variable definition has a **unique** name
  - Each variable use refers to a single definition
- ▶ SSA simplifies **data flow analysis** and many compiler optimizations
  - Eliminates artificial dependences (on scalars)
    - Write-after-write
    - Write-after-read

# SSA within a Basic Block

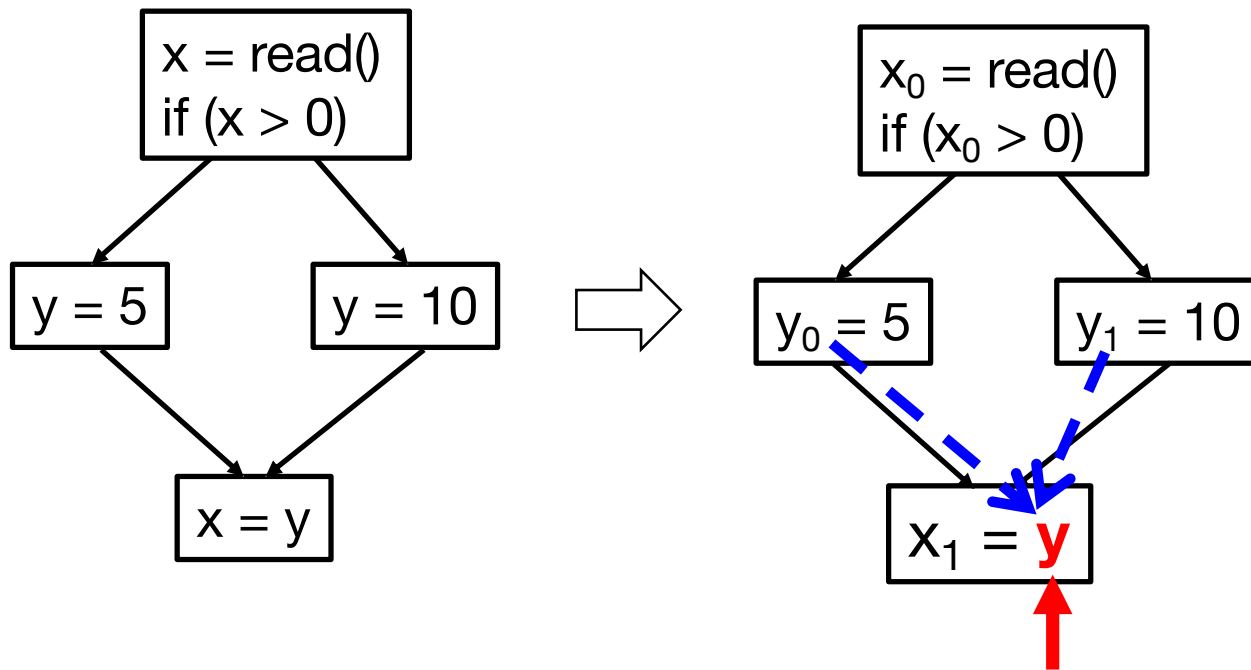
- ▶ Assign each variable definition a unique name
- ▶ Update the uses accordingly



# SSA with Control Flow

- ▶ Consider a situation where two control-flow paths merge
  - e.g., due to an if-then-else statement or a loop

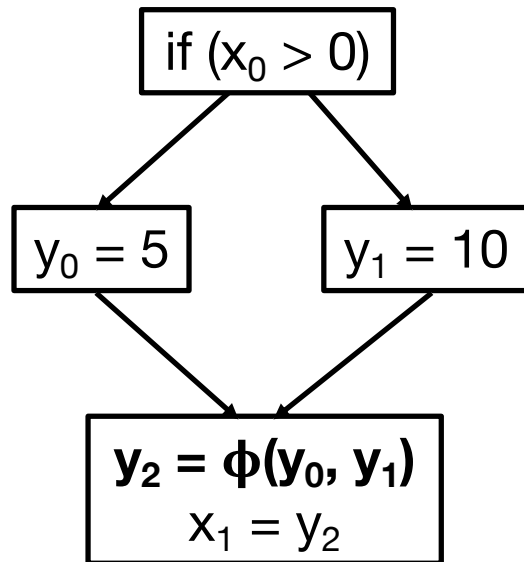
```
x = read()
if (x > 0)
  y = 5
else
  y = 10
x = y
```



should this be  $y_0$  or  $y_1$ ?

## Introducing $\phi$ -Node

- ▶ Inserts special join functions (called  **$\phi$ -nodes** or PHI nodes) at points where different control flow paths converge

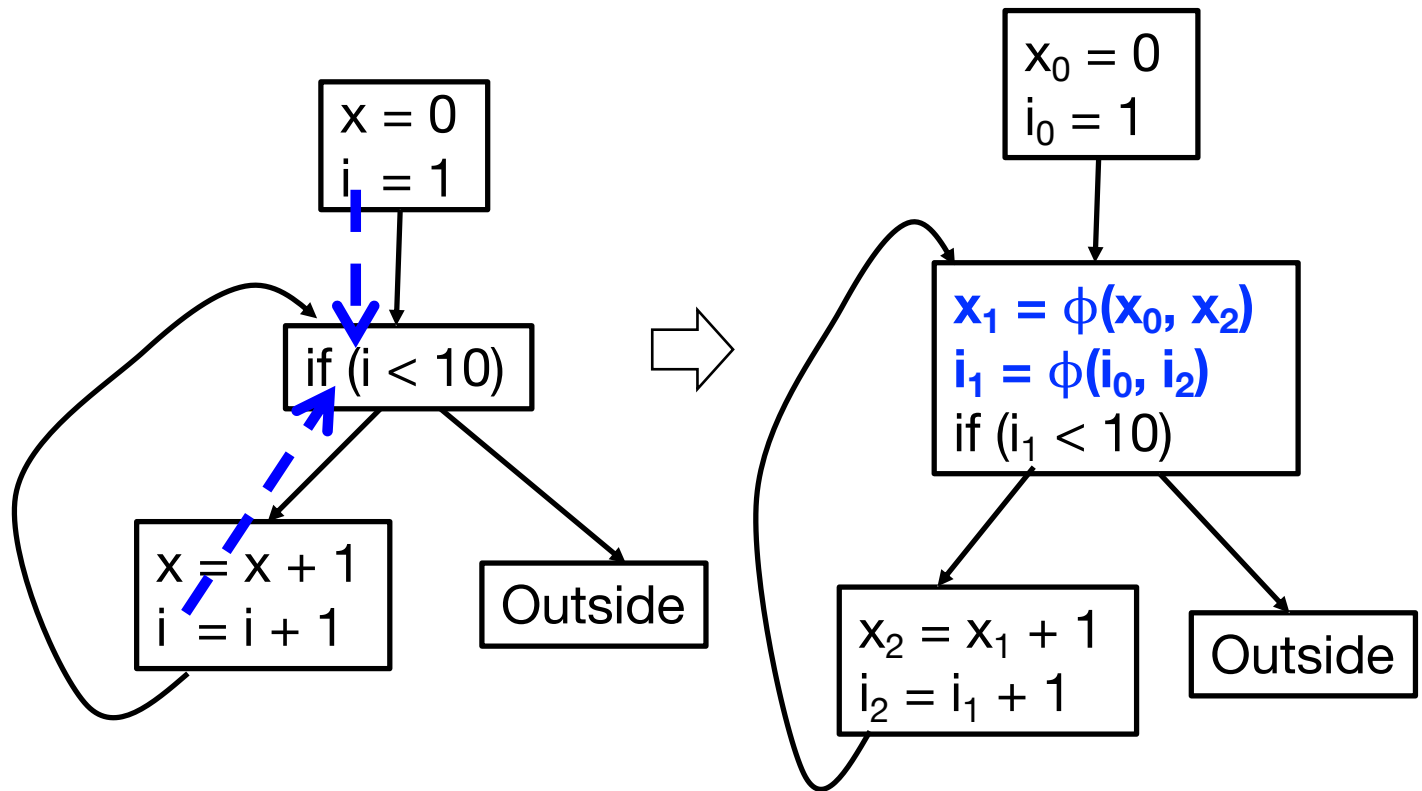


**Note:  $\phi$  is not an executable function!**  
To generate executable code from this form, appropriate copy statements need to be generated in the predecessors (in other words, reversing the SSA process for code generation)

# SSA in a Loop

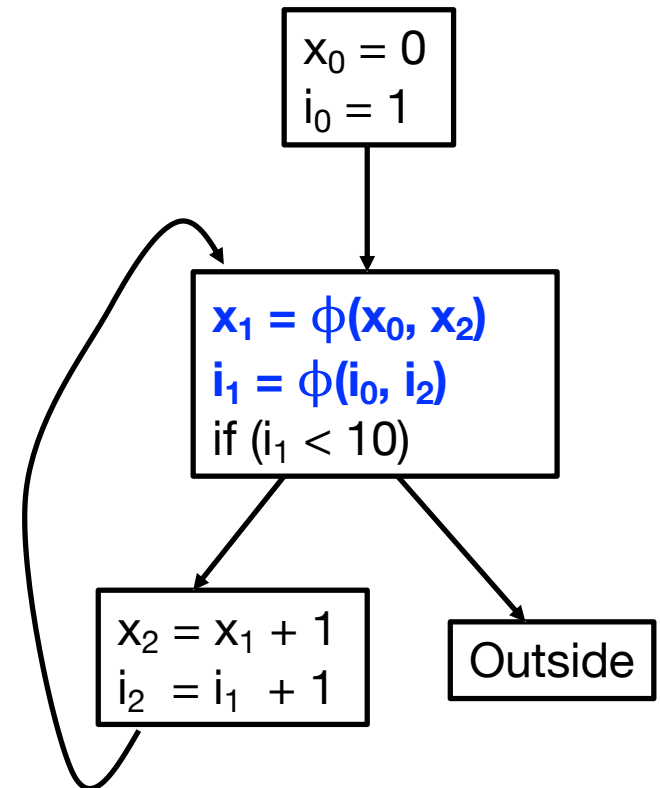
- ▶ Insert  $\phi$ -nodes in the loop header block

```
x = 0
i = 1
while (i < 10) {
  x = x + i
  i = i + 1
}
```



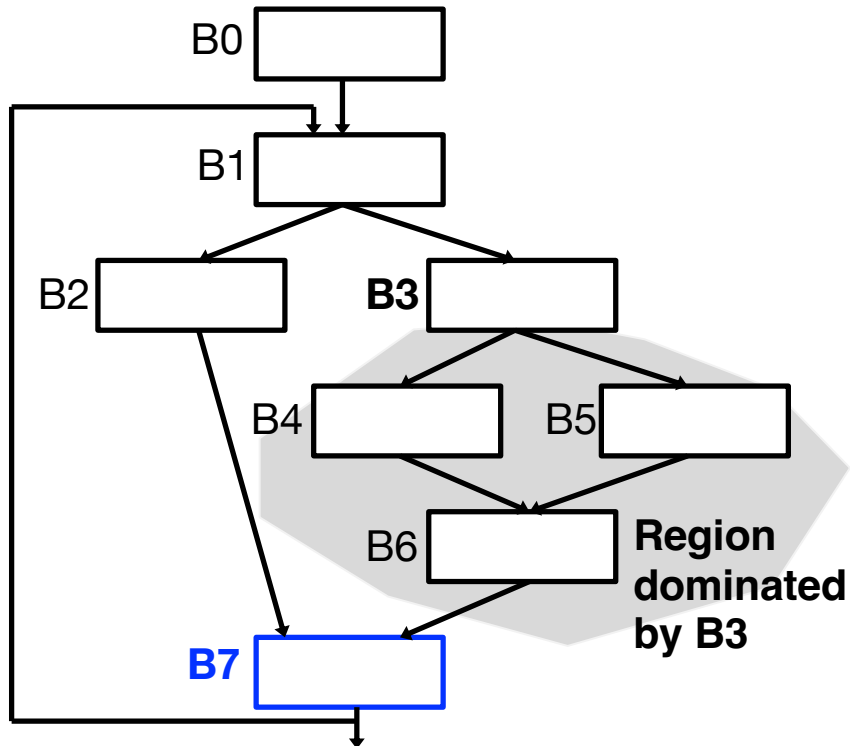
# $\phi$ -Node Placement

- ▶ When and where to insert  $\phi$ -nodes?
  - If two control paths  $A \rightarrow C$  and  $B \rightarrow C$  converge at a node  $C$ , and both  $A$  and  $B$  contain assignments to variable “ $x$ ”, then  $\phi$ -node for “ $x$ ” must be placed at  $C$ 
    - We call  $C$  a **join node or convergence point**
    - Generalizes to more than two converging control paths
- ▶ Objective: Minimize the number of  $\phi$ -nodes
  - Need to compute dominance frontier sets





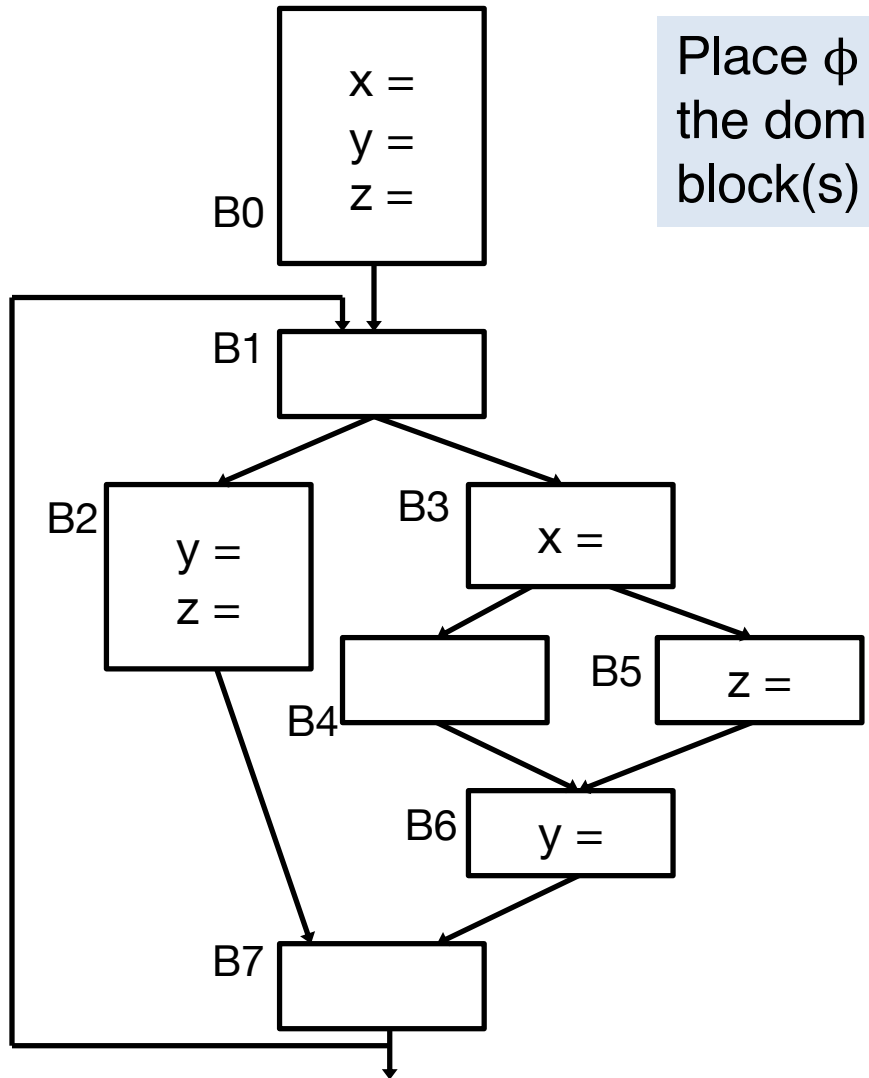
# Example: Dominance Frontier and SSA



- ▶ B7 is in the dominance frontier set of B3
  - In other words, B7 is the destination of some edge(s) leaving a region dominated by B3
- ▶ **For each variable definition in B3, a  $\phi$  node is needed in B7**

# $\phi$ -Node Placement

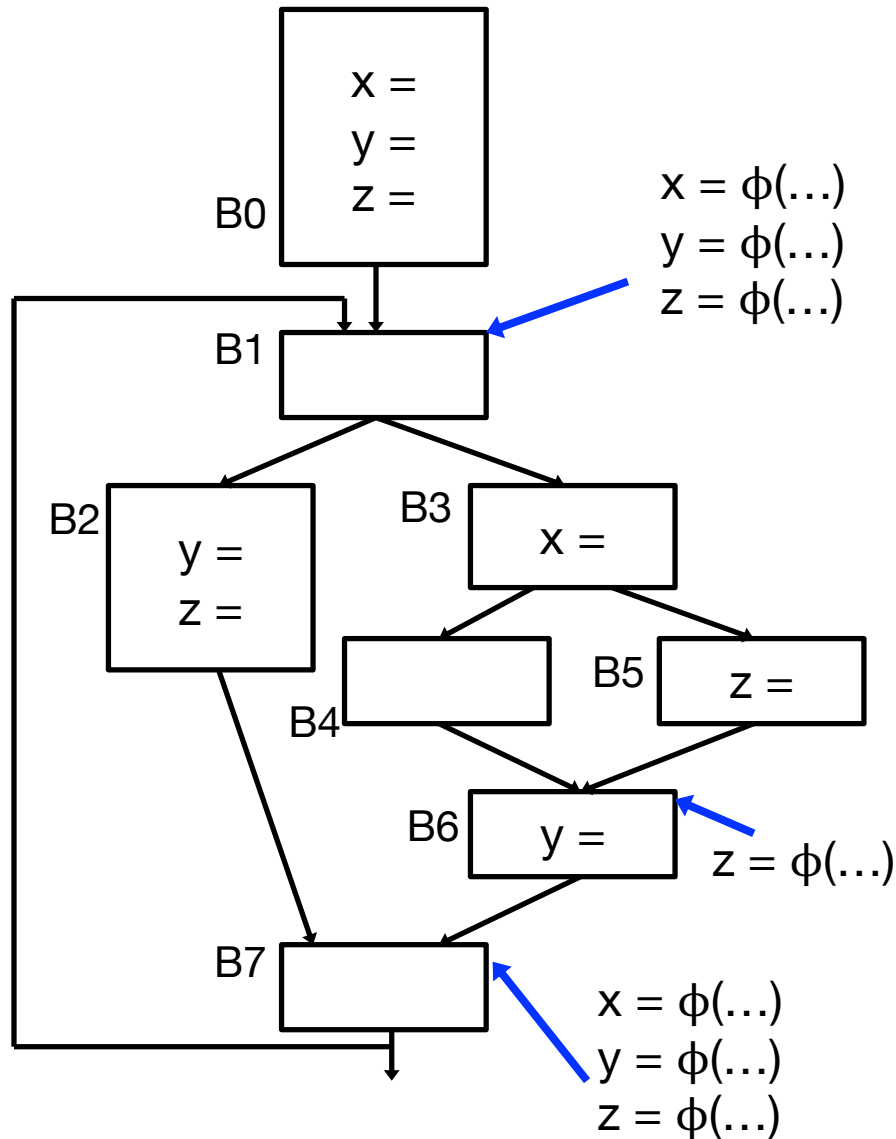
p	DF
0	-
1	1
2	7
3	7
4	6
5	6
6	7
7	1



Place  $\phi$  node(s) of a variable  $x$  in the dominance frontier set of the block(s) where  $x$  gets defined

# $\phi$ -Node Placement: Iterative Insertion

p	DF
0	-
1	1
2	7
3	7
4	6
5	6
6	7
7	1



- $x$  is defined in 0, 3  
 $\Rightarrow$  insert  $\phi$  in 7,  
then  $x$  also defined in 7  
 $\Rightarrow$  insert  $\phi$  in 1
- $y$  is defined in 0, 2, 6  
 $\Rightarrow$  insert  $\phi$  in 7  
then  $y$  also defined in 7  
 $\Rightarrow$  insert  $\phi$  in 1
- $z$  is defined in 0, 2, 5  
 $\Rightarrow$  insert  $\phi$  in 6, 7  
then  $z$  also defined in 7  
 $\Rightarrow$  insert  $\phi$  in 1

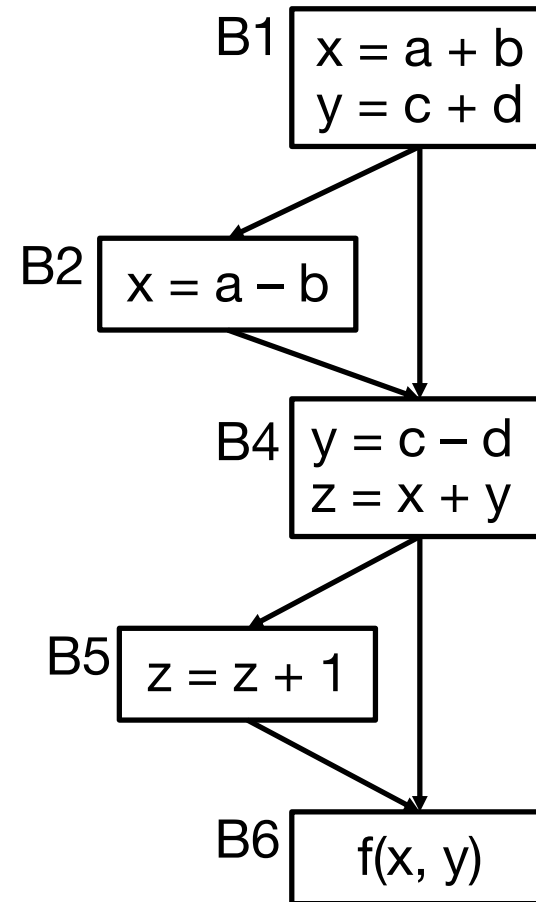
Afterwards, assign a unique name to each variable definition (including  $\phi$  nodes) and update all uses

# SSA Applications

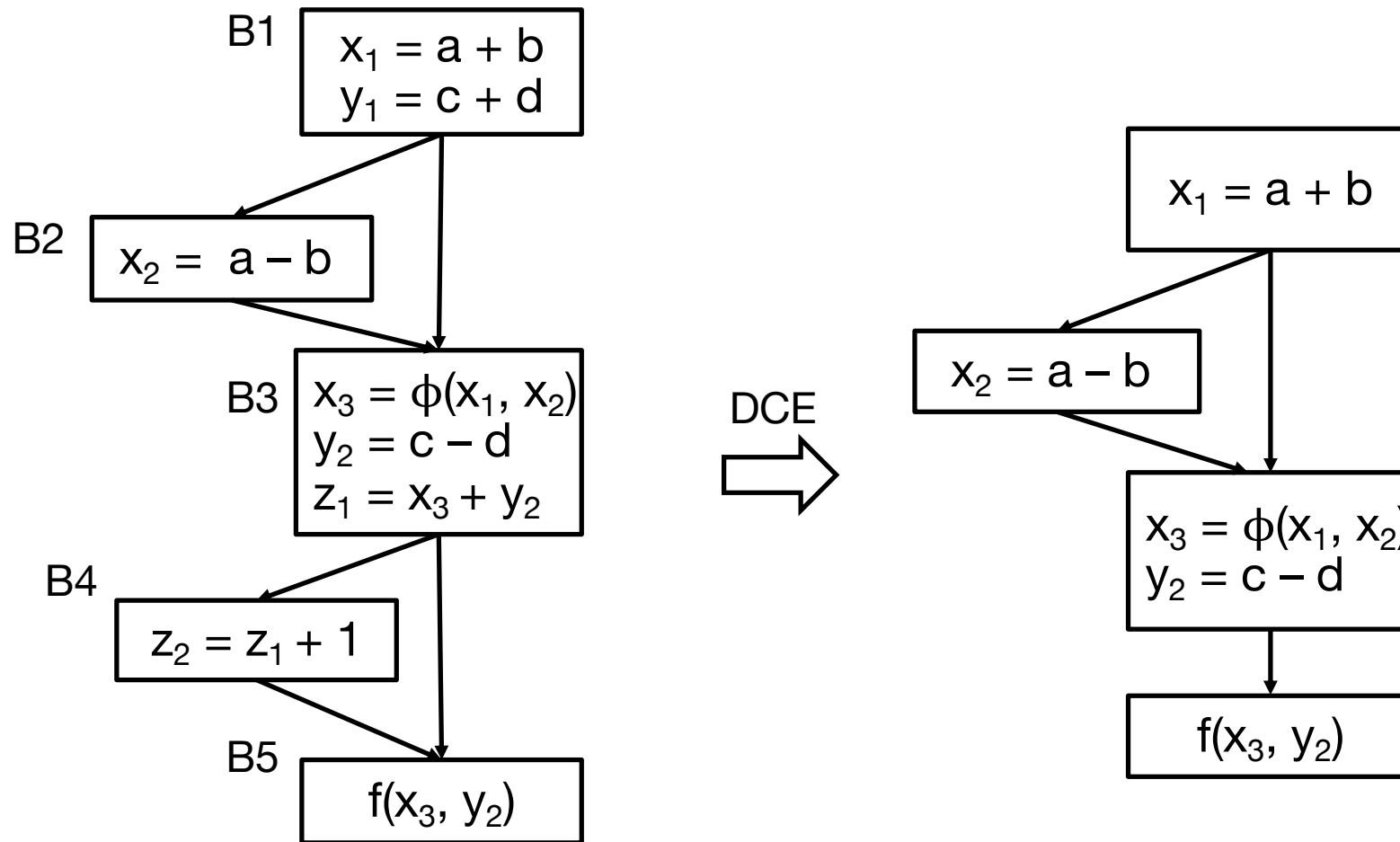
- ▶ SSA form simplifies data flow analysis and many code transformations
  - Primarily due to explicit & simplified (sparse) def-use chains
- ▶ Here we show two simple examples
  - Dead code elimination
  - Loop induction variable detection

# Dead Code in CDFG

- ▶ A dead statement is either
  - (1) Unreachable code
  - (2) Definitions never used
- ▶ How to efficiently Identify the dead statements?



# Dead Code Elimination (DCE) with SSA



**Iteratively remove unused definitions**

first remove  $y_1$ ,  $z_2$ , and B4; then remove  $z_1$

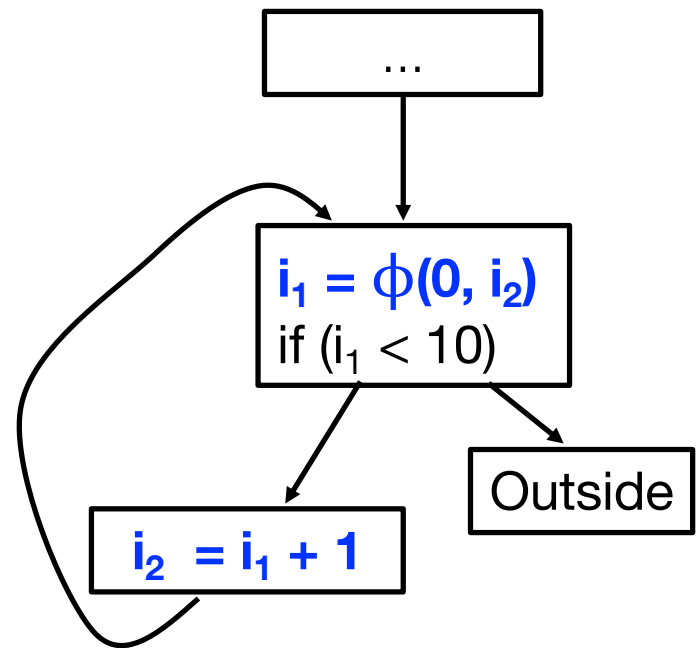
# Loop Induction Variables

- ▶ An induction variable is a variable that
  - Gets increased or decreased by a fixed amount (loop invariant) on every iteration of a loop
    - $i = i + c$  (**basic induction variable**)
  - or is an affine function of another induction variable
    - $j = a * i + b$  (**mutual induction variable**)

# Identifying Basic Loop Induction Variable

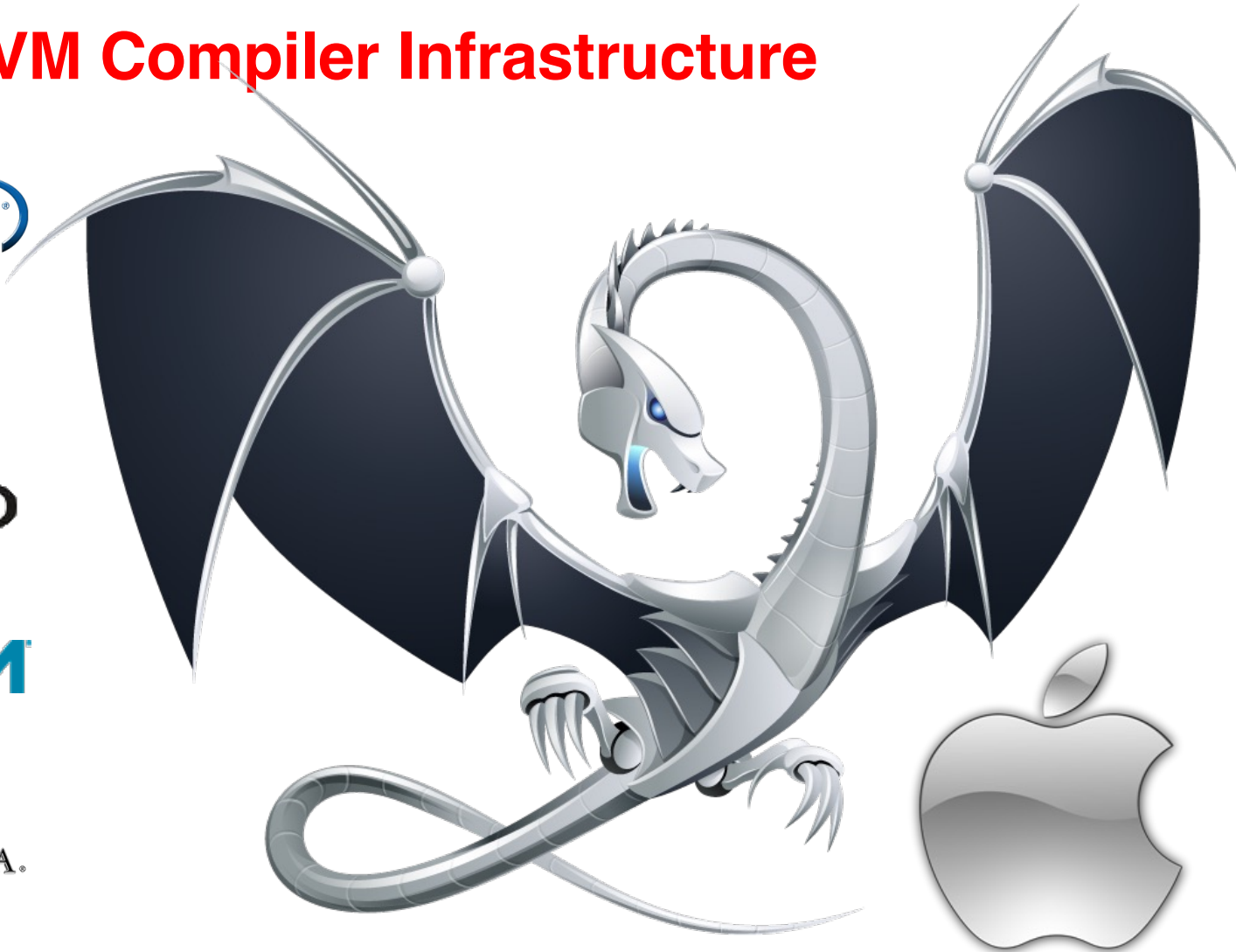
► Find basic loop induction variable(s)

1. Inspect back edges in the loop
2. Each back edge points to a  $\phi$  node in the loop header, which may indicate a basic induction variable
3.  $\phi$  is a function of an initialized variable and a definition in the form of “ $i + c$ ” (i.e., increment operation)





# LLVM Compiler Infrastructure



**LLVM is not Compiler but a Compiler Infrastructure**

# What is LLVM?

- ▶ Formerly Low Level Virtual Machine
  - Brainchild of Chris Lattner and Vikram Adve back in 2000
  - [ACM Software System Award](#) in 2012
- ▶ **The core of LLVM is the SSA-base IR**
  - Language independent, target independent, easy to use
  - RISC-like virtual instructions, unlimited registers, exception handling, etc.
- ▶ Provides modular & reusable components for building compilers
  - Components are ideally language/target independent
  - Allows choice of the right component for the job
  - Many high-quality libraries (components) with clean interfaces
    - Optimizations, analyses, modular code generator, profiling, link time optimization, ARM/X86/PPC/SPARC code generator ...
    - Tools built from the libraries: C/C++/ObjC compiler, modular optimizer, linker, debugger, LLVM JIT ...

# The Structure of a Program in LLVM

- ▶ Module contains Functions/GlobalVariables
  - Module is unit of compilation/analysis/optimization
- ▶ Function contains BasicBlocks/Arguments
  - Functions roughly correspond to functions in C
- ▶ BasicBlock contains list of instructions
  - Each block ends in a control flow instruction
- ▶ Instruction is opcode + vector of operands
  - All operands have types
  - Instruction result is typed

# Example: An LLVM Loop

```
loop:  
  %i.1 = phi i5 [ 0, %bb0 ], [ %i.2, %loop ]  
  %AiAddr = getelementptr float* %A, i32 %i.1  
  call void @foo(float %AiAddr, %pair* %P)  
  %i.2 = add i5 %i.1, 1  
  %tmp = icmp eq i5 %i.1, 16  
  br i1 %tmp, label %loop, label %outloop
```

```
for (i=0; i<N; ++i)  
  foo(A[i], &P);
```

- ▶ High-level information exposed in the code
  - Explicit dataflow through SSA form
  - Explicit control-flow graph
  - Explicit language-independent type-information
  - Explicit typed pointer arithmetic
    - Preserve array subscript and structure indexing

# Arbitrary Precision Integers in LLVM

- ▶ LLVM is adopted in several commercial and academic HLS tools
- ▶ It has built-in support for arbitrary width integers since version 2.0 (e.g., i2, i128, i1024)
  - Essential for hardware synthesis
  - An 11b multiplier is significantly cheaper/faster than a 16b implementation
  - Can leverage other LLVM analyses/optimizations to perform bitwidth minimization

# LLVM Flow Analysis

- ▶ LLVM IR is in SSA form
  - use-def and def-use chains are always available
  - All objects have user/use info, even functions
- ▶ Control flow graph (CFG) is always available
  - Exposed as BasicBlock predecessor/successor lists
  - Many generic graph algorithms usable with the CFG
- ▶ Higher-level info implemented as passes
  - CallGraph, Dominators, LoopInfo, ...

## Next Lecture

- ▶ Scheduling

# Acknowledgements

- ▶ These slides contain/adapt materials developed by
  - Prof. Scott Mahlke (UMich)
  - Dr. Chris Lattner (Modular AI)