

ECE 2400 Computer Systems Programming, Fall 2017

Prelim 2 Prep

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These problems are not meant to be exactly like the problems that will be on the prelim. These problems are instead meant to represent the kind of understanding you should be able to demonstrate on the prelim.

In the following problems, we will explore two different data structures to track the directory hierarchy in an operating system. The data hierarchy could be used to store metadata about each directory in the system (e.g., number of files in each directory, access control for the directory), and the operating system would provide an *application level interface* (API) to enable system-level software to read and write the directory hierarchy. For example, the following commands will make four directories and then display the directory hierarchy.

```
1 % mkdir foo
2 % mkdir foo/bar0
3 % mkdir foo/bar1
4 % mkdir foo/bar0/baz
5 % tree
```

The directory hierarchy is made up of directories where each *parent directory* can have one or more *child directories*. So in the above example, `foo` is the parent of `bar0` and `bar1`. Or equivalently, `bar0` and `bar1` are the children of `foo`.

We will explore two data structures to store the directory hierarchy. The data structures should support making new directories and printing the full directory hierarchy. For this problem, you can assume that the maximum number of directories in the system is 16 and that there are no more than four child directories in any given parent directory. There are two common errors that we might want our data structure to check:

- **Directory Already Exists:** The data structure should cause an error if the user attempts to make a directory that already exists. *For this problem you are required to correctly detect this error and throw an `std::invalid_argument` exception.*
- **Parent of Directory Does Not Exist:** Ideally, the data structure should cause an error if the user attempts to create a new directory where one or more of the parents of that directory do not exist. *To simplify the problem, you can assume the user never attempts to create a new directory unless all of the parents of that directory already exist.*

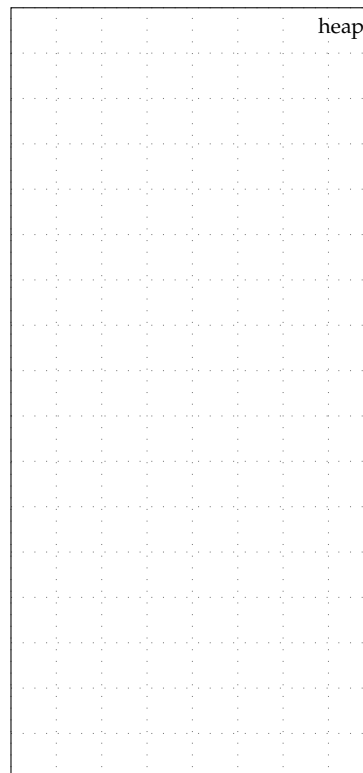
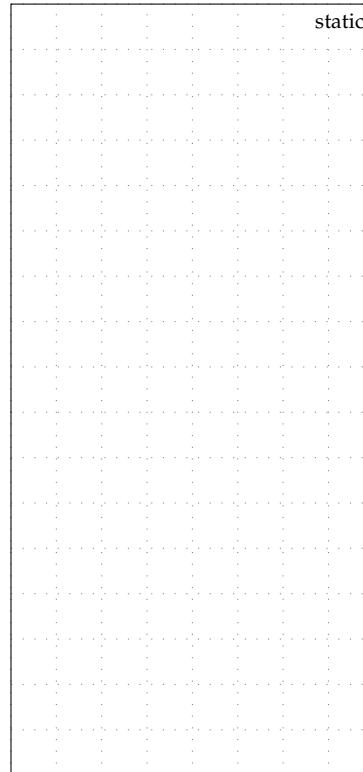
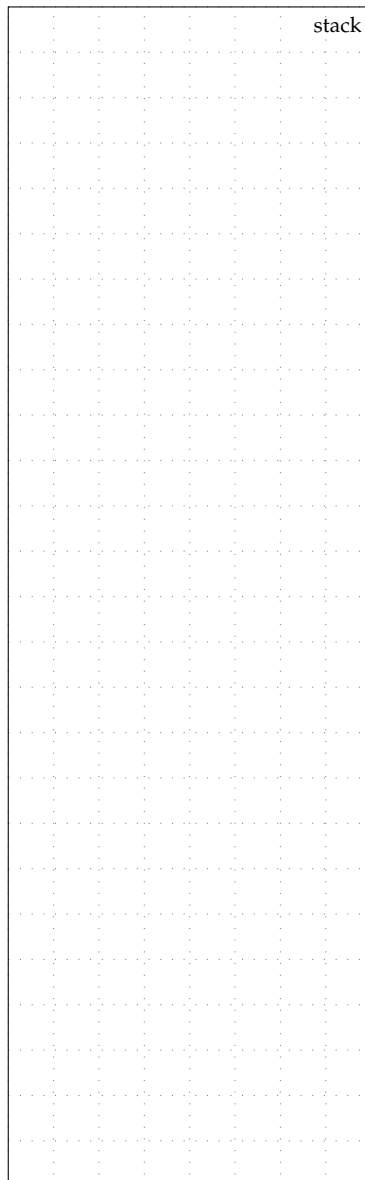
Part 1.B Algorithm Analysis for DirList

For this analysis assume we wish to store N paths in the directory hierarchy. **What is the best- and worst-case time complexity for `mkdir` as a function of N ? What is the space complexity of this data structure as a function of N ?**

Part 1.C Storage Diagram for DirList

Consider the following usage of DirList. Draw the storage diagram corresponding to the state of this C program after line 4.

```
1 int main( void )
2 {
3     DirList dl;
4     dl.mkdir( "foo" );
5     return 0;
6 }
```



Problem 2. Tree-Based Director Hierarchy Data Storage

Our second data structure uses a *tree*. A tree is like a linked list, except every node can have more than one “next node”. The class declaration is as follows:

```

1  class DirTree
2  {
3  public:
4
5      DirTree() : m_root(Node()) { }
6
7      void mkdir( std::string path );
8
9      void print()
10     {
11         for ( size_t i = 0; i < m_root.children_size; i++ )
12             print_h( "", m_root.children[i] );
13     }
14
15 private:
16
17     class Node {
18     public:
19
20         Node( const std::string dir_ = "" )
21             : dir(dir_), children_size(0)
22         { }
23
24         std::string dir;
25         size_t      children_size;
26         Node*       children[4];
27     };
28
29     size_t split( std::string dirs[], std::string path )
30     {
31         size_t i = 0;
32         auto pos = path.find("/");
33         while ( pos != std::string::npos ) {
34             dirs[i] = path.substr(0,pos);
35             i++;
36             path.erase( 0, pos+1 );
37             pos = path.find("/");
38         }
39         dirs[i] = path.substr(0,pos);
40         i++;
41         return i;
42     }
43
44     void print_h( const std::string& prefix, Node* node_p );
45
46     Node m_root;
47
48 };

```


Part 2.B Implementing DirTree::print_h

Implement the `print_h` private helper member function. This should be a recursive function which prints out the current path corresponding to the given `Node` pointer and then recursively processes the current node's children.

```
1 void DirTree::print_h( const std::string& prefix, Node* node_p )
2 {
3     std::string new_prefix = prefix + "/" + node_p->name;
```

Part 2.C Algorithm Analysis of DirTree

For this analysis assume we wish to store N paths in the directory hierarchy. **What is the best-case and worst-case time complexity for `mkdir` as a function of N ? What is the space complexity of this data structure as a function of N ?**