

ECE 2400 Computer Systems Programming

Fall 2017

Topic 10: Sorting Algorithms

School of Electrical and Computer Engineering
Cornell University

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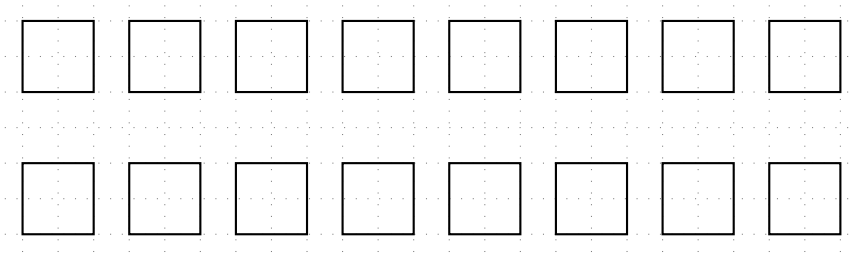
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- We will explore three kinds of algorithms:
 - **Out-of-Place Algorithms:** Gradually copy elements from input array into a temporary array; by the end the temporary array is sorted; $O(N)$ space complexity
 - **In-Place Algorithms:** Keep all elements stored in the input array; use input array for intermediate results; no temporary storage is required; $O(1)$ space complexity
 - **Hybrid Algorithms:** Initially use one algorithm, but switch to a different algorithm sometime during the sorting process
- For each algorithm we will use
 - Cards to build intuition behind algorithm
 - Pseudocode to make algorithm more concrete
 - Visual pseudocode to precisely illustrate algorithm
 - Complexity analysis

1. Insertion Sort

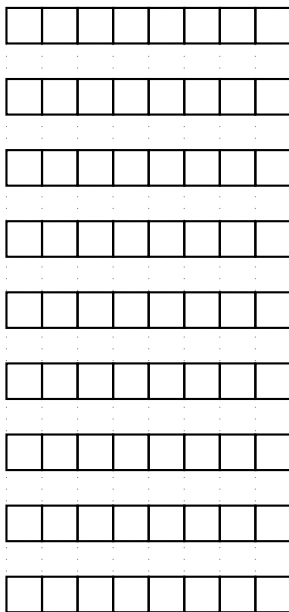
- Take elements out of input array and insert them into a sorted output array such that the output array remains sorted

1.1. Out-of-Place Insertion Sort



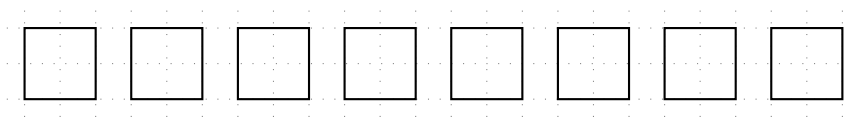
```
1 isort_op( a, size )
2   set tmp to an empty array of with size elements
3   for i in 0 to size-1 (inclusive) # iterate over input
4     temp = a[i]
5     for j in 0 to i-1 (inclusive) # iterate over output
6       if temp < tmp[j]
7         swap( temp, tmp[j] )
8     tmp[i] = temp
9   return tmp
```

- Show contents of tmp for each iteration of outer loop



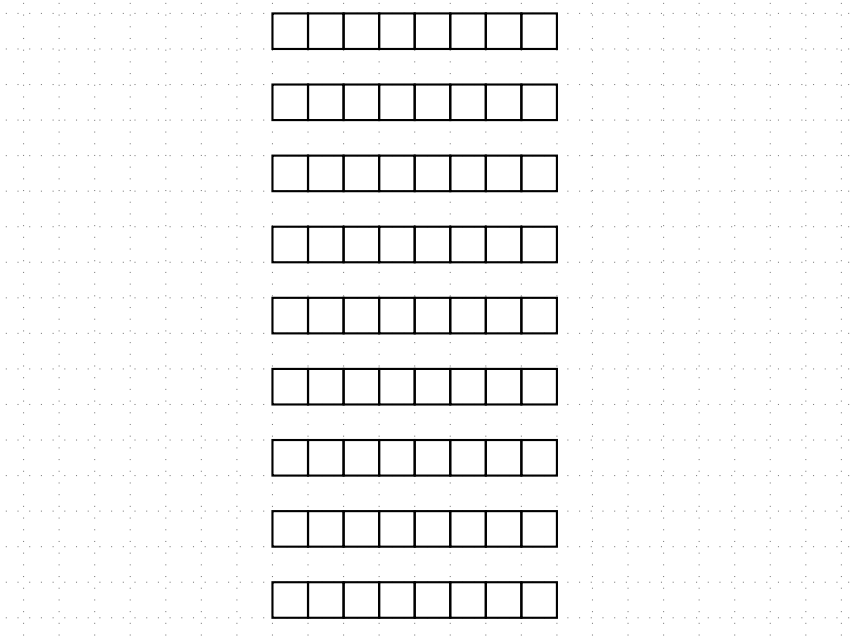
- Space complexity is $O(N)$ due to temporary array b
- Worst-case time complexity analysis
 - Assume C_0 is time spent in one iteration of outer loop excluding any time spent in inner loop
 - Assume C_1 is time spent in one iteration of inner loop

1.2. In-Place Insertion Sort (forward search)



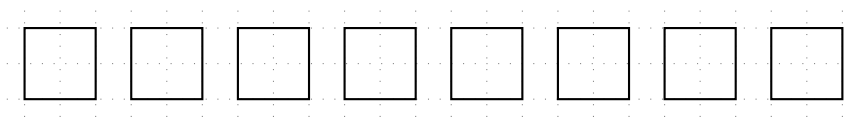
```
1 isort_ip_fwd( a, size )
2   for i in 0 to size-1 (inclusive) # iterate over input
3     temp = a[i]
4     for j in 0 to i-1 (inclusive) # iterate over sorted
5       if temp < a[j]:             # region
6         swap( temp, a[j] )
7     a[i] = temp
8   return a
```

- Show contents of a for each iteration of outer loop



- Space complexity is $O(1)$, no temporary array
- Worst-case time complexity analysis
 - Assume C_0 is time spent in one iteration of outer loop excluding any time spent in inner loop
 - Assume C_1 is time spent in one iteration of inner loop

1.3. In-Place Insertion Sort (reverse search)



```
1 isort_ip_rev( a, size )
2   for i in 1 to size-1 (inclusive)
3     for j in i-1 to 0 (inclusive)
4       if a[j+1] < a[j]
5         swap( a[j], a[j+1] )
6       else                                     # stop once new value
7         break                                 # is in the right position
8   return a
```

- Space complexity is $O(1)$, no temporary array
- Worst-case time complexity analysis
 - Assume C_0 is time spent in one iteration of outer loop excluding any time spent in inner loop
 - Assume C_1 is time spent in one iteration of inner loop

- Best-case time complexity analysis
 - Assume input array is already sorted

1.4. Activity

- Use in-place insertion sort
- Show contents of `a` for each iteration of outer loop

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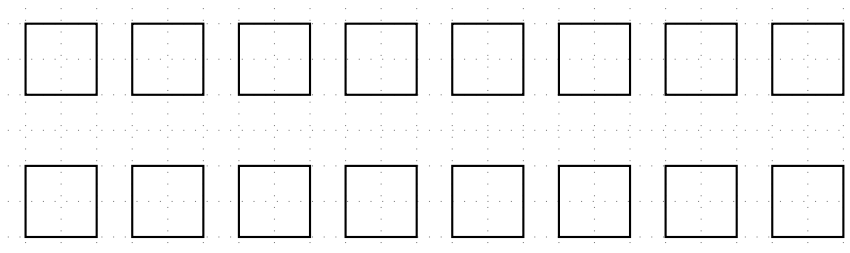
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2. Selection Sort

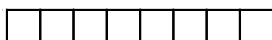
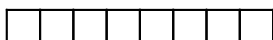
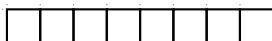
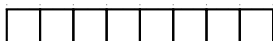
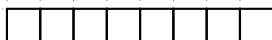
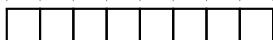
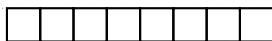
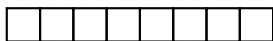
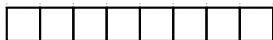
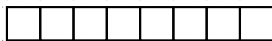
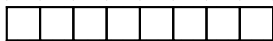
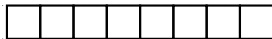
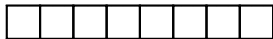
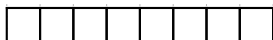
- Select minimum element from input array and add this element to the end of the sorted output array such that the output array remains sorted

2.1. Out-of-Place Selection Sort



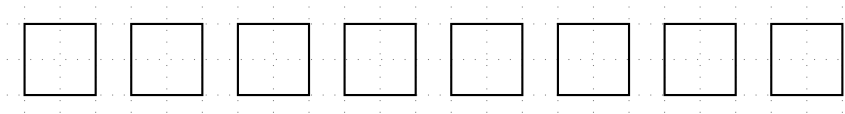
```
1 ssort_op( a, size )
2   set tmp to an empty array of with size elements
3   for i in 0 to size-1 (inclusive)
4       min_value = a[0]                # Find the minimum
5       min_idx   = 0
6       for j in 0 to size-i-1 (inclusive)
7           if min_value > a[j]
8               min_value = a[j]
9               min_idx   = j
10      for j in min_idx to size-i-2 (inclusive) # Remove the minimum
11          a[j] = a[j+1]
12      tmp[i] = min_value                # Put minimum in output
13  return tmp
```

- Show contents of a and b for each iteration of outer loop



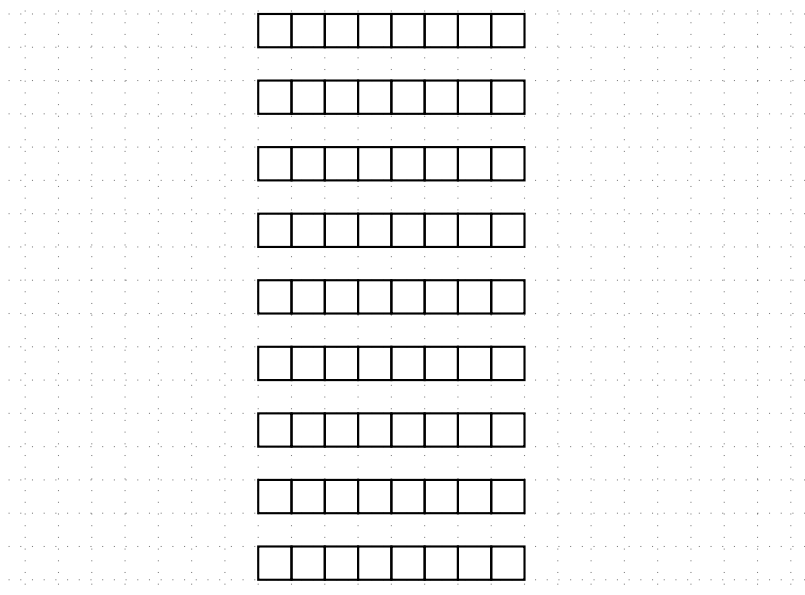
- Space complexity is $O(N)$ due to temporary array b
- Worst-case time complexity analysis
 - Assume C_0 is time spent in one iteration of outer loop excluding any time spent in inner loops
 - Assume C_1 is time spent in one iteration of first inner loop
 - Assume C_2 is time spent in one iteration of second inner loop

2.2. In-Place Selection Sort



```
1 ssort_ip( a, size )
2   for i in 0 to size-1 (inclusive)
3
4       min_value = a[i]                # Find the minimum
5       min_idx   = i
6       for j in i to size-1 (inclusive)
7           if min_value > a[j]
8               min_value = a[j]
9               min_idx   = j
10
11       swap( a[min_idx], a[i] )        # Swap the minimum
12
13   return a
```

- Show contents of a for each iteration of outer loop



- Space complexity is $O(N)$ due to temporary array b
- Worst-case time complexity analysis
 - Assume C_0 is time spent in one iteration of outer loop excluding any time spent in the inner loop
 - Assume C_1 is time spent in one iteration of inner loop

2.3. Activity

- Use in-place selection sort
- Show contents of `a` for each iteration of outer loop

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3. Merge Sort

- Recursively partition input array into smaller partitions
- Base case is when one element is in a partition
- Merge two sorted partitions into a larger partition

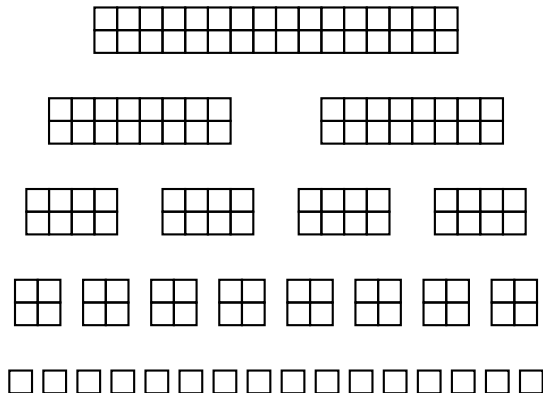
```
1 msort_op( a, size )
2
3   if ( size == 1 )
4       return a
5
6   left_size = size/2
7   right_size = size - left_size
8   left = msort2_op( a[0:left_size], left_size )
9   right = msort2_op( a[left_size:size], right_size )
10
11   set tmp to an empty array of with size elements
12   left_idx = 0; right_idx = 0
13
14   for k in 0 to size-1 (inclusive)
15
16       # Done with left array
17       if ( left_idx == left_size )
18           tmp[k] = right[right_idx]; right_idx += 1
19
20       # Done with right array
21       elif ( right_idx == right_size )
22           tmp[k] = left[left_idx]; left_idx += 1
23
24       # Front of left is less than front of right
25       elif ( left[left_idx] < right[right_idx] )
26           tmp[k] = left[left_idx]; left_idx += 1
27
28       # Front of right is less than front of less
29       else:
30           tmp[k] = right[right_idx]; right_idx += 1
31
32   return tmp
```


3. Merge Sort

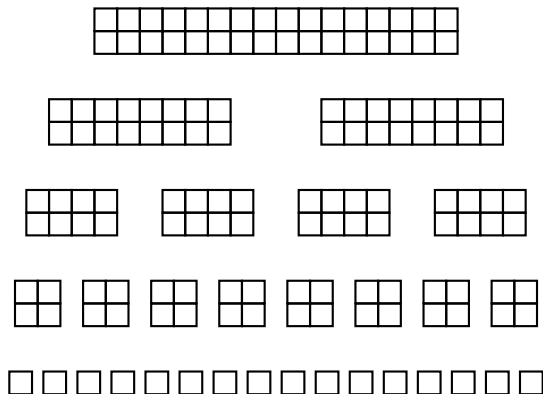
- Show contents of `a` for each recursive call
- Show contents of `tmp` for each merge

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- Worst-case time complexity analysis
 - Assume C_0 is time spent in one iteration of merge loop
 - Assume C_1 is time spent in base case



- Space complexity analysis



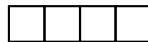
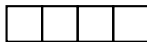
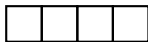
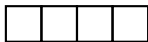
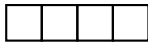
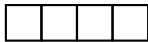
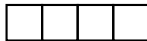
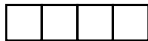
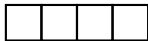
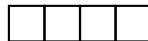
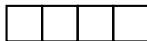
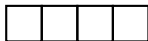
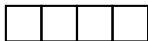
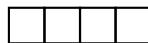
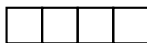
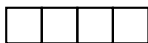
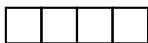
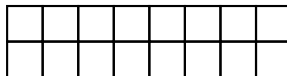
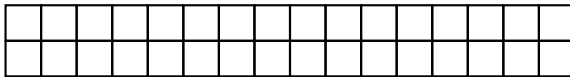
3.1. Hybrid Merge/Insertion Sort

- Once array becomes small enough, use $O(N^2)$ sort

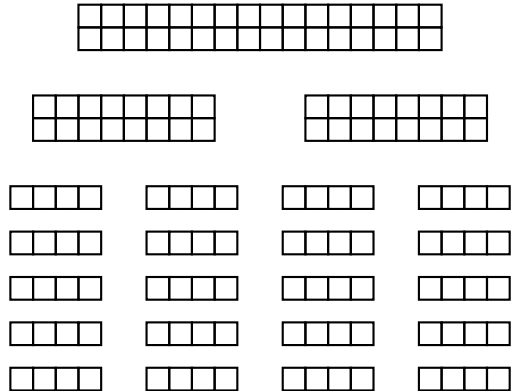
```

1 msort_hybrid( a, size )
2   if ( size <= 4 )
3       return isort_op( a, size )
4   ...

```



- Worst-case time complexity analysis
 - Assume C_0 is time spent in one iteration of merge loop
 - Assume C_2 is time spent in one iteration of isort inner loop



4. Quick Sort

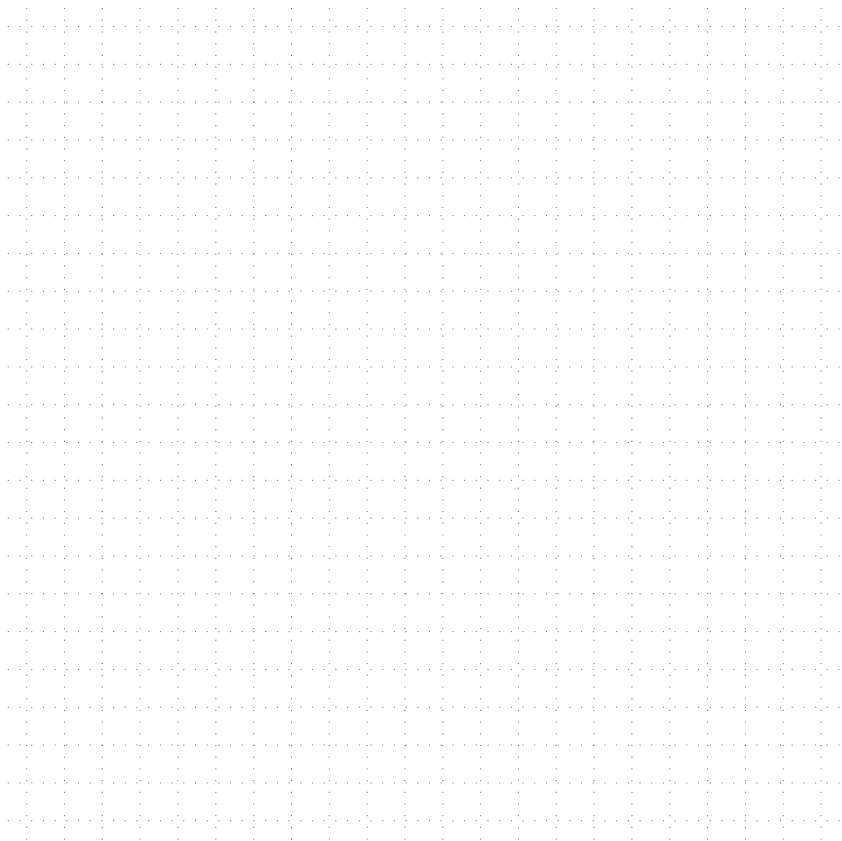
4.1. Out-of-Place Quick Sort

- Pick a pivot element to partition input array into two partitions
- All elements less than the pivot are in first partition
- All elements more than the pivot are in second partition
- Now know position of pivot
- Recursively sort each of the two partitions

```
1 qsort_op( a, size )
2
3   if ( size <= 1 )
4       return a
5
6   pivot = a[size-1]
7
8   left      = []
9   left_size = 0
10  right     = []
11  right_size = 0
12  for i in 0 to size-2 (inclusive)
13      if ( a[i] < pivot )
14          left.append(a[i])
15          left_size += 1
16      else:
17          right.append(a[i])
18          right_size += 1
19
20  left = qsort_op( left, left_size )
21  right = qsort_op( right, right_size )
22  return left + [pivot] + right
```



- Time complexity analysis



4.2. In-Place Quick Sort

```
1 partition( A, lo, hi )
2   pivot = a[hi]
3   i = lo - 1
4   for j in lo to hi-1 (inclusive)
5       if ( a[j] < pivot )
6           i = i + 1
7           swap( a[j], a[i] )
8
9   if ( a[hi] < a[i+1] )
10       swap( a[hi], a[i+1] )
11
12   return i + 1
13
14 qsort_ip_h( a, lo, hi )
15   if ( lo < hi )
16       p = partition( a, lo, hi )
17       qsort_ip_h( a, lo, p - 1 )
18       qsort_ip_h( a, p + 1, hi )
19
20 qsort_ip( a, size )
21   qsort_ip_h( a, 0, size-1 )
22   return a
```


5. Radix Sort

5.1. Out-of-Place Radix Sort

5.2. Activity