


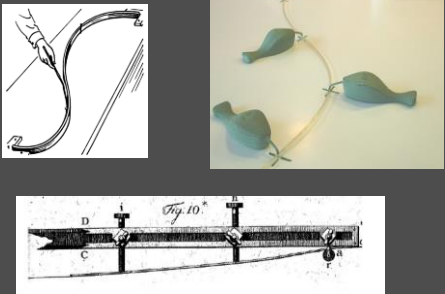
Intro to Computer Graphics

Geometric Modeling Part II

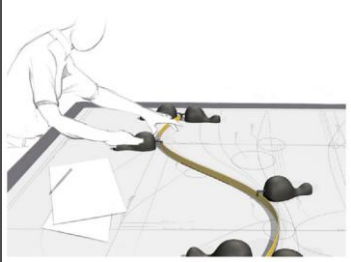


Physical Splines

Curve design pre-computers



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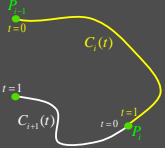


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Cubic Splines

- Standard spline input – set of points $\{P_i\}_{i=0, n}$
 - No derivatives specified as input
- Interpolate by n cubic segments ($4n$ DOF):
 - Force C^1 and C^2 continuity at points
 - Solve $4n$ linear equations in $4n$ unknowns

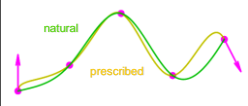
Interpolation ($2n$ equations):
 $C_i(0) = P_{i-1}$ $C_i(1) = P_i$ $i = 1, \dots, n$
 C^1 continuity constraints ($n-1$ equations):
 $C_i(1) = C_{i+1}(0)$ $i = 1, \dots, n-1$
 C^2 continuity constraints ($n-1$ equations):
 $C_i'(1) = C_{i+1}'(0)$ $i = 1, \dots, n-1$



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Cubic Splines

- Have two degrees of freedom left (to reach $4n$ DOF)
- Options
 - Natural end conditions: $C_1''(0) = 0, C_n''(1) = 0$
 - Complete end conditions: $C_1'(0) = 0, C_n'(1) = 0$
 - Prescribed end conditions (derivatives available at the ends):
 $C_1'(0) = T_0, C_n'(1) = T_n$
 - Periodic end conditions
 $C_1(0) = C_n(1), C_1'(0) = C_n'(1)$



Question: What parts of $C(t)$ are affected as a result of a change in P_i ?

demo

Basis functions should be local

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Parameterization

- The assumption $t \in [0, 1]$ (uniform parameterization) is arbitrary
 - Implicitly implies same curve "length" for each segment
- Not natural if points are not equally spaced
- One alternative - chord-length parameterization:

Denote $d_i = \sqrt{(P_{i+1}^x - P_i^x)^2 + (P_{i+1}^y - P_i^y)^2}$
 For the i 'th segment : $t \in [0, d_i]$.

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Parameterization

Chord-length

Uniform

[0,1] [0,8] [0,1] [0,3] [0,1] [0,4]

[0,1] [0,1] [0,3] [0,1] [0,4]

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Bezier Curves

- Bezier curve is an **approximation** of given control points
- Denote by $C(t)$: $t \in [0,1]$
- Bezier curve of degree n is defined over $n+1$ control points $\{P_i\}_{i=0,n}$

Order 6 Bézier

Order 3 Bézier

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De Casteljau Construction

Select $t \in [0,1]$ value.

```

For i := 0 to n do  $P_i^{[0]}(t) := P_i$ ;
For j := 1 to n do
  For i := j to n do
     $P_i^{[j]}(t) := (1-t)P_{i-1}^{[j-1]}(t) + tP_i^{[j-1]}(t)$ ;
 $C(t) := P_n^{[n]}(t)$ ;
    
```

$t = 1/3$

$C(1/3)$

demo

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Algebraic Form of Bezier Curves

Bezier curve for set of control points $\{P_i\}_{i=0,n}$:

$$C(t) = \sum_{i=0}^n P_i B_i^n(t) = \sum_{i=0}^n P_i \binom{n}{i} (1-t)^{n-i} t^i$$

$\{B_i^n(t)\}_{i=0,n} =$ Bernstein basis of polynomials of degree n

Cubic case:

- $B_0^3(t) = (1-t)^3$
- $B_1^3(t) = 3(1-t)^2 t$
- $B_2^3(t) = 3(1-t) t^2$
- $B_3^3(t) = t^3$

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Algebraic Form of Bezier Curves

$$C(t) = \sum_{i=0}^n P_i \binom{n}{i} (1-t)^{n-i} t^i$$

- $\sum_{i=0}^n B_i^n(t) = 1, \forall t \in [0,1]$
- why?
 - Curve is linear combination of basis functions
 - Curve is convex combination of control points

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Properties of Bezier Curves

$$C(t) = \sum_{i=0}^n P_i \binom{n}{i} (1-t)^{n-i} t^i$$

- $C(t)$ is polynomial of degree n
- $C(t) \in \text{CH}(P_0, \dots, P_n)$
- $C(0) = P_0$ and $C(1) = P_n$
- $C(t)$ is a Bezier curve of one degree less
- $C'(0) = n(P_1 - P_0)$ and $C'(1) = n(P_n - P_{n-1})$
- $C(t)$ is affine invariant and variation diminishing

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Properties of Bezier Curves

- Questions:
 - What is the shape of Bezier curves whose control points lie on one line?
 - How can one connect two Bezier curves with C^0 continuity? C^1 ? C^2 ?

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Drawbacks of Bezier Curves

- Degree corresponds to number of control points
 - Global support: change in one control point affects the entire curve
 - For large sets of points – curve deviates far from the points
- Cannot represent conics exactly. Most noticeably circles
 - Can be resolved by introducing a more powerful representation of *rational curves*.
 - For example, a 90 degrees arc as a rational Bezier curve:

$$C(t) = \frac{w_0 P_0 B_0^2(t) + w_1 P_1 B_1^2(t) + w_2 P_2 B_2^2(t)}{w_0 B_0^2(t) + w_1 B_1^2(t) + w_2 B_2^2(t)}$$

where $\frac{w_0 w_2}{w_1^2} = 2$.

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Recap

Bernstein basis functions:

$$B_i^n(t) = \binom{n}{i} (1-t)^{n-i} t^i \quad \forall t \in [0,1], \forall i \quad B_i^n(t) > 0, \quad \sum_{i=0}^n B_i^n(t) = 1$$

Bezier curve is *linear* combination of basis functions:

$$C(t) = \sum_{i=0}^n P_i B_i^n(t)$$

Bezier curve is *convex* combination of control points (combination depends on t):

$$C(t) = \sum_{i=0}^n P_i B_i^n(t)$$

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B-Spline Curves

Idea: Generate basis of functions with *local support*

$$C(t) = \sum_{i=0}^{n-1} P_i N_i(t)$$

- For each parameter value only a finite set of basis functions is non-zero
- The parametric domain is partitioned into sections at integer parameter values (called *knots*).

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Cubic B-Spline Basis

$$C(t) = \sum_{i=0}^{n-1} P_i N_i(t), \quad t \in [3, n]$$

$$N_i(t) = \begin{cases} r^3/6 & r=t-i & t \in [i, i+1) \\ (-3r^3 + 3r^2 + 3r + 1)/6 & r=t-(i+1) & t \in [i+1, i+2) \\ (3r^3 - 6r^2 + 4)/6 & r=t-(i+2) & t \in [i+2, i+3) \\ (1-r)^3/6 & r=t-(i+3) & t \in [i+3, i+4) \end{cases}$$

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Cubic B-Spline Basis

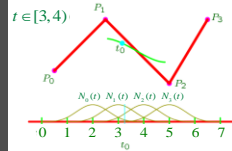
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Cubic B-Spline Basis

- For any $t \in [3, n]$: $\sum_{i=0}^{n-1} N_i(t) = 1$
- For any $t \in [3, n]$ at most four basis functions are non zero
- Any point on a cubic B-Spline is a convex combination of at most *four* control points

$$C(t) = \sum_{i=0}^{n-1} P_i N_i(t)$$



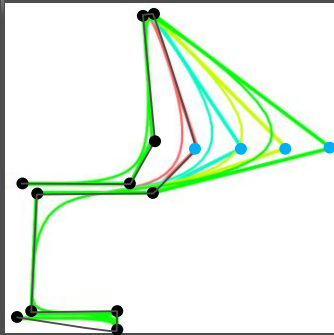
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Boundary Conditions for Cubic B-Spline Curves

- B-Splines do not interpolate control points
 - in particular, the uniform cubic B-spline curves do not interpolate the end points of the curve.
- Ways to force endpoint interpolation:
 - Let $P_0 = P_1 = P_2$ (same for other end)
 - Add a new control point (same for other end) $P_{-1} = 2P_0 - P_1$ and a new basis function $N_{-1}(t)$.

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Local Control of B-spline Curves



Control point P_i affects $C(t)$ only for $t \in (i, i+4)$

[demo](#)

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Properties of B-Spline Curves

- $C(t) = \sum_{i=0}^{n-1} P_i N_i(t)$, $t \in [3, n]$
- For n control points, $C(t)$ is a piecewise polynomial of degree 3, defined over $t \in [3, n]$
- $C(t) \in \bigcup_{i=0}^{n-4} CH(P_i, \dots, P_{i+3})$
- $C(t)$ is *affine invariant* and *variation diminishing*
- Questions:
 - What is $C(i)$ equal to?
 - What is $C(i+1)$ equal to?
 - What is the continuity of $C(t)$? Prove!

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From Curves to Surfaces

- A curve is expressed as inner product of coefficients P_i and basis functions
- Treat surface as a *curve of curves*. Also known as *tensor product surfaces*
- Assume P_i is not constant, but are functions of a second, new parameter v :

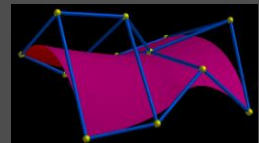
$$C(u) = \sum_{i=0}^n P_i B_i(u)$$

$$P_i(v) = \sum_{j=0}^m Q_{ij} B_j(v)$$

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From Curves to Surfaces (cont'd)

$$\begin{aligned} C(u) &= \sum_{i=0}^n P_i B_i(u) \\ &= \sum_{i=0}^n \left(\sum_{j=0}^m Q_{ij} B_j(v) \right) B_i(u) \\ &= \sum_{i=0}^n \sum_{j=0}^m Q_{ij} B_j(v) B_i(u) \end{aligned}$$

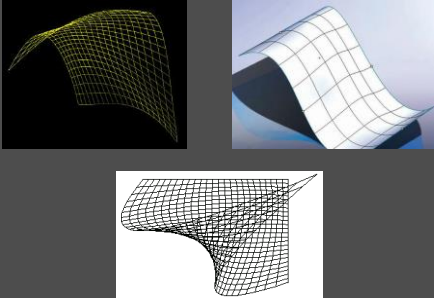


$$S(u, v) = \sum_{i=0}^n \sum_{j=0}^m Q_{ij} B_j(v) B_i(u)$$

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Isoparametric Curves



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Surface Constructors

- Construction of the geometry is a first stage in any *image synthesis* process
- Use a set of high level, simple and intuitive, surface constructors:
 - Bilinear patch
 - Ruled surface
 - Boolean sum
 - Surface of revolution
 - Extrusion surface
 - Swept surface

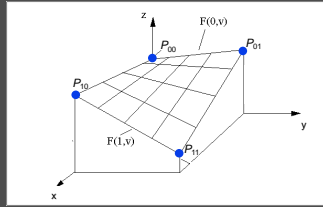
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Bilinear Patches

- Bilinear interpolation of 4 3D points - 2D analog of 1D linear interpolation between 2 points in the plane
- Given $P_{00}, P_{01}, P_{10}, P_{11}$ the bilinear surface for $u, v \in [0, 1]$ is:

$$P(u, v) = (1-u)(1-v)P_{00} + (1-u)vP_{01} + u(1-v)P_{10} + uvP_{11}$$

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$$P(u, v) = (1-u)(1-v)P_{00} + (1-u)vP_{01} + u(1-v)P_{10} + uvP_{11}$$



Questions:

- What does an isoparametric curve of a bilinear patch look like ?
- Can you represent the bilinear patch as a Bezier surface ?
- When is a bilinear patch planar ?

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Ruled Surfaces

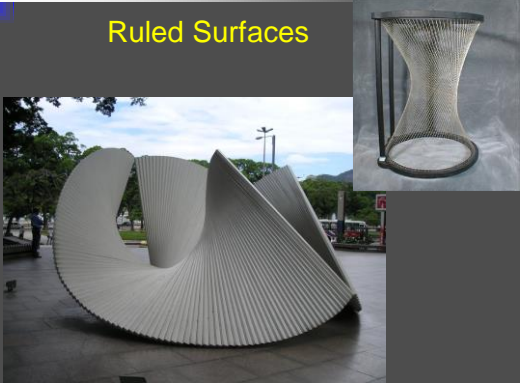
- Given two curves $a(t)$ and $b(t)$, the corresponding ruled surface between them is:

$$S(u, v) = v a(u) + (1-v)b(u)$$


- The corresponding points on $a(u)$ and $b(u)$ are connected by straight lines
- Questions:
 - When is a ruled surface a bilinear patch?
 - When is a bilinear patch a ruled surface?

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Ruled Surfaces



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Boolean Sum

- Given four connected curves α_i $i=1,2,3,4$, Boolean sum $S(u, v)$ fills the interior.

$$P(u, v) = (1-u)(1-v)P_{00} + (1-u)vP_{01} + u(1-v)P_{10} + uvP_{11}$$

$$S_1(u, v) = v\alpha_0(u) + (1-v)\alpha_2(u)$$

$$S_2(u, v) = u\alpha_1(v) + (1-u)\alpha_3(v)$$

Then

$$S(u, v) = S_1(u, v) + S_2(u, v) - P(u, v)$$

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Boolean Sum (cont'd)

- $S(u, v)$ interpolates the four α_i along its boundaries.
- For example, consider the $u = 0$ boundary:

$$S(0, v) = S_1(0, v) + S_2(0, v) - P(0, v)$$

$$= v\alpha_0(0) + (1-v)\alpha_2(0) + 0\alpha_1(v) + 1\alpha_3(v) - (1-v)P_{00} - vP_{01}$$

$$= vP_{01} + (1-v)P_{00} + \alpha_3(v) - (1-v)P_{00} - vP_{01}$$

$$= \alpha_3(v)$$

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Surface of Revolution

- Rotate a, usually planar, curve around an axis
- Consider curve $\beta(t) = (\beta_x(t), 0, \beta_z(t))$ and let Z be the axis of revolution.

$$x(u, v) = \beta_x(u) \cos(v)$$

$$y(u, v) = \beta_x(u) \sin(v)$$

$$z(u, v) = \beta_z(u)$$

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Surfaces of Revolution

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Extruded Surface

- Extrusion of a, usually planar, curve along a linear segment.
- Given curve $\beta(t)$ and vector \vec{v}

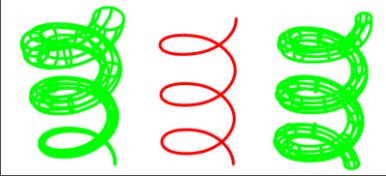
$$S(u, v) = \beta(u) + v\vec{v}$$

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Swept Surface

- ❑ Rigid motion of one (cross section) curve along another (axis) curve:



- ❑ The cross section may change as it is swept

Question: Is an extrusion a special case of a sweep?
a surface of revolution?

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